

NVIDIA AUTONOMOUS DRIVING PLATFORM

Apr, 2017 Sr. Solution Architect , Marcus Oh

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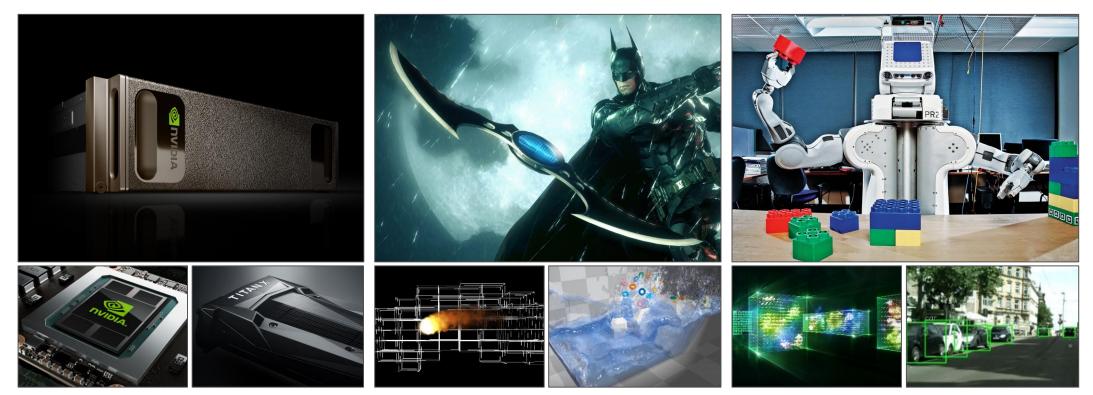
Who is NVIDIA Deep Learning in Autonomous Driving Training Infra & Machine / DIGIT DRIVE PX2 DRIVEWORKS USECASE Example Next Generation AD Platform

NVIDIA

Founded in 1993 | CEO & Co-founder: Jen-Hsun Huang | FY16 revenue: \$5.01B | 9,500 employees | 7,300 patents | HQ in Santa Clara, CA |



NVIDIA — "THE AI COMPUTING COMPANY"



GPU Computing

Computer Graphics

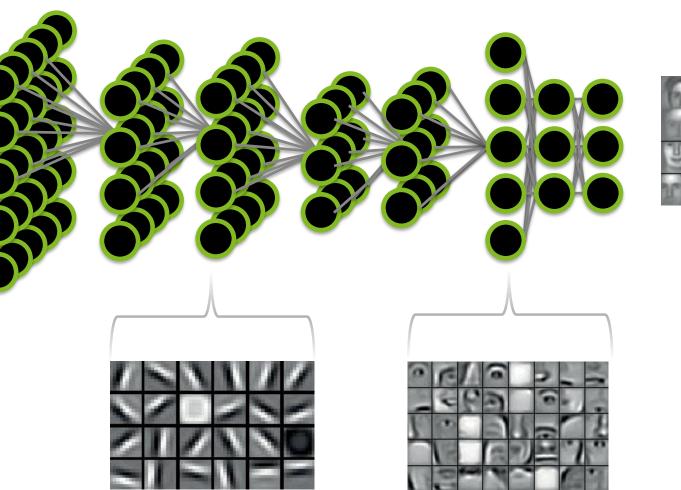
Artificial Intelligence

DEEP LEARNING IN AUTONOMOUS DRIVING

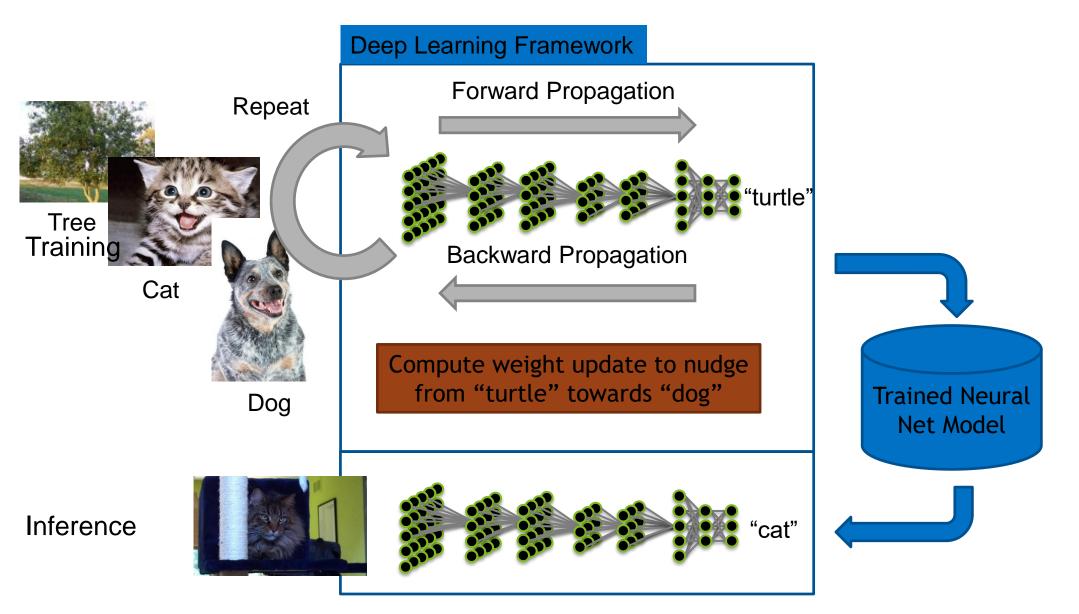
WHAT IS DEEP LEARNING?



Input



Result

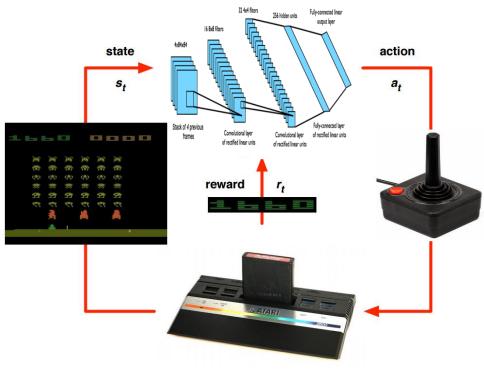




REINFORCEMENT LEARNING

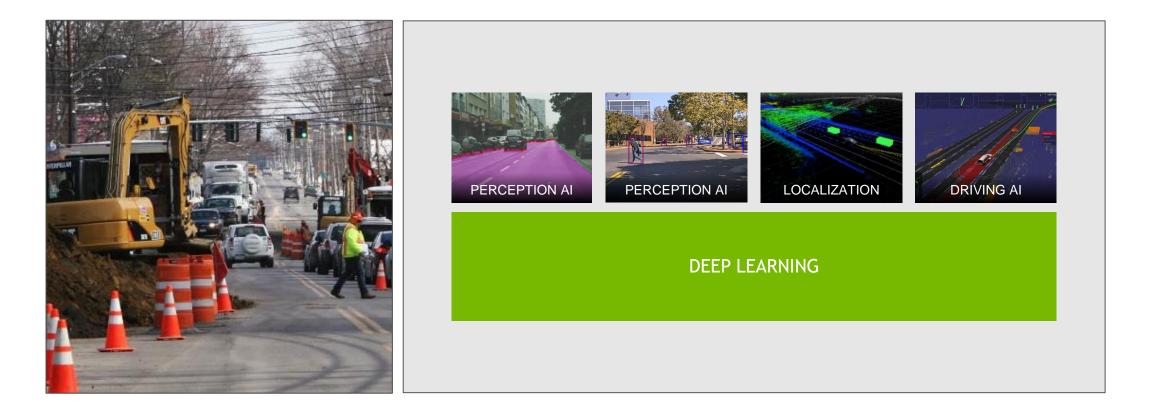
How's it work?

- A reinforcement learning agent includes:
 - state (environment)
 - actions (controls)
 - reward (feedback)
- A value function predicts the future reward of performing actions in the current state
 - Given the recent state, action with the maximum estimated future reward is chosen for execution
- For agents with complex state spaces, deep networks are used as Q-value approximator
 - Numerical solver (gradient descent) optimizes the network on-the-fly based on reward inputs



github.com/dusty-nv/jetson-reinforcement

SELF-DRIVING CARS ARE AN AI CHALLENGE

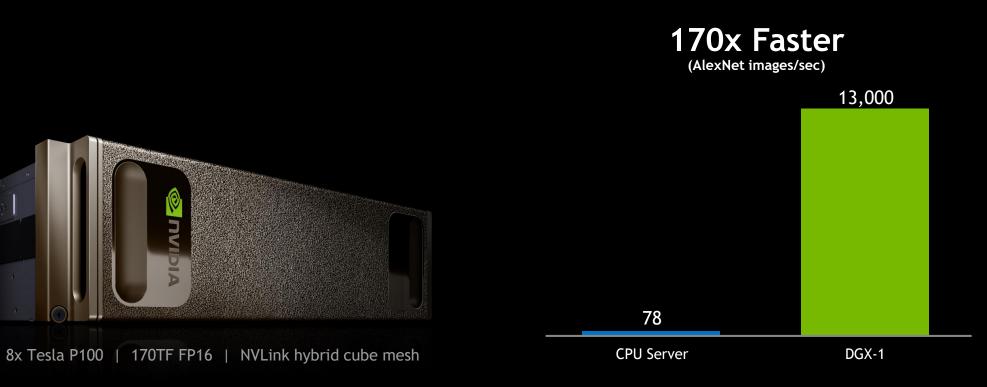


NVIDIA AI SYSTEM FOR AUTONOMOUS DRIVING

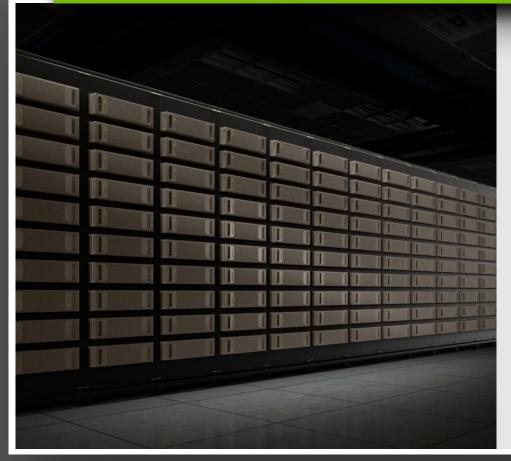


TRAINING INFRA & MACHINE / DIGIT

170X SPEED-UP OVER COTS SERVER MICROSOFT COGNITIVE TOOLKIT SUPERCHARGED ON NVIDIA DGX-1



INTRODUCING DGX SATURNV 124 NVIDIA DGX-1 "Rocket for Cancer Moonshot"





Fastest AI Supercomputer in TOP500 4.9 Petaflops Peak FP64 19.6 Petaflops Peak FP16



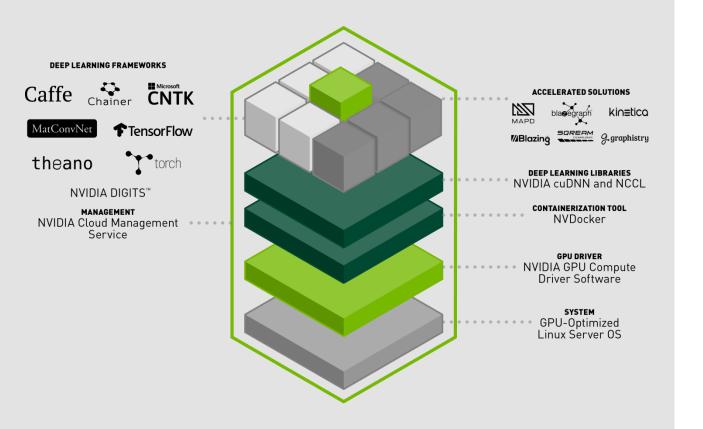
Most Energy Efficient Supercomputer #1 Green500 9.5 GFLOPS per Watt



Rocket for Cancer Moonshot CANDLE Development Platform Common platform with DOE labs — ANL, LLNL, ORNL, LANL

DGX STACK

Fully integrated Analytics and Deep Learning platform



Instant productivity — plug-andplay, supports every AI framework and accelerated analytics software applications

Performance optimized across the entire stack

Always up-to-date via the cloud

Mixed framework environments – baremetal and containerized

Direct access to NVIDIA experts



DIGIT Deep Learning GPU Training System

- Design, train and visualize deep neural networks for image classification, segmentation and object detection
- Download pre-trained models such as AlexNet, GoogLeNet and LeNet from the DIGITS Model Store
- Perform hyperparameter sweep of learning rate and batch size for improved model accuracy
- Schedule, monitor, and manage neural network training jobs, and analyze accuracy and loss in real time
- Import a wide variety of image formats and sources
- Scale training jobs across multiple GPUs automatically





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Visualize deep neural network architectures

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NVIDIA SELF-DRIVING BUILDING BLOCKS Accelerate your development and deployment

SELF DRIVING TECHNOLOGY



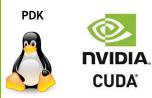






TOOLS

SOFTWARE





cuDNN









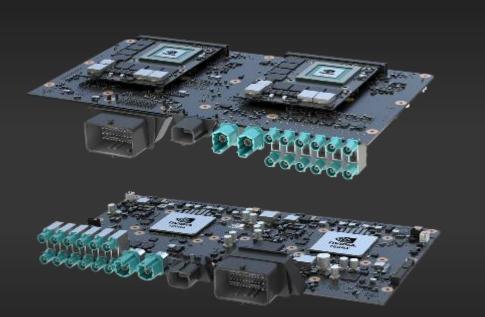






NVIDIA DRIVE PX 2 AUTOCRUISE

10W AI Car Computer | Passive Cooling | Automotive IO Multiple Cameras & Sensors | DriveWorks SW/SDK AI Highway Driving | Localization & HD Mapping Tegra Parker SoC – 1.3 TFLOPS, 6 CPU Cores, Integrated ISP



NVIDIA DRIVE PX 2 AUTOCHAUFFEUR & FULLY AUTONOMOUS

Scalable from 1 to 4 Processors to Multiple DRIVE PX 2s - 2x Tegra Parker SoC, 2x Pascal dGPU, 8 TFLOPS, 24 DNN TOPs Up to 12 Cameras; plus LIDAR, Radar, Ultrasonic sensors DriveWorks SW/SDK | Al Perception | Localization & Mapping



TensorRT: INFERENCE ENGINE

Optimizations



- Eliminate concatenation layers
- Kernel specialization
- Auto-tuning for target platform
- Tuned for given batch size

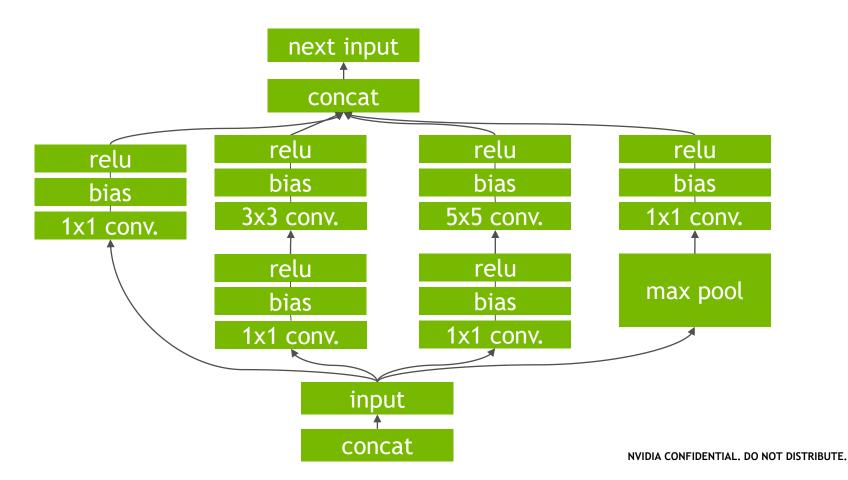


developer.nvidia.com/tensorrt

TRAINED NEURAL NETWORK

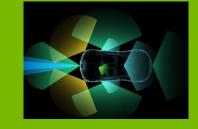
GRAPH OPTIMIZATION

Unoptimized network



21 💿 NVIDIA.





DRIVEWORKS

Software Development Kit (SDK) for Autonomous Driving

Process sensor data through Perception, Mapping, Localization, and Path Planning steps

Provides a rich set of functionalities:

Sensor Abstraction Layer (SAL)

Algorithm Modules, DNNs

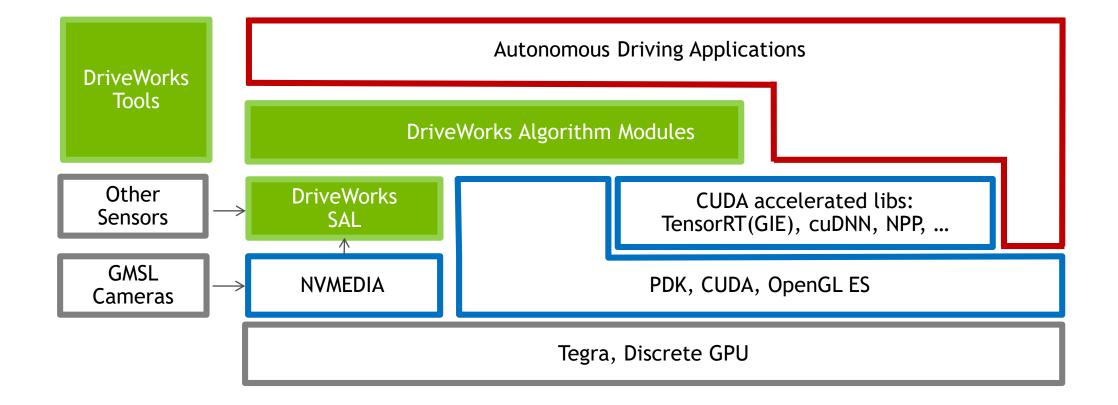
Applications

Tools for sensor setup and management

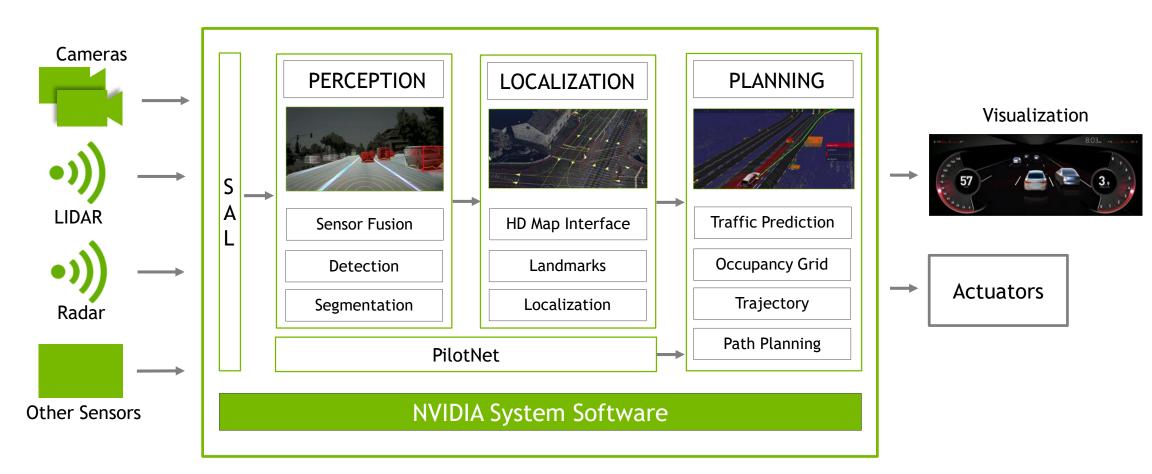
Flexible, modular and optimized for GPU

Runs on top of OS, CUDA/CuDNN, TensorRT, VPI

SOFTWARE STACK WITH DRIVEWORKS

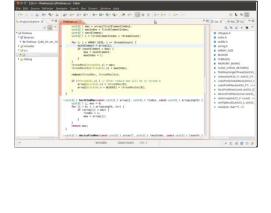


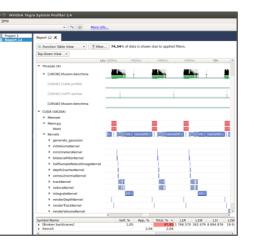
DRIVEWORKS PROCESSING PIPELINE End-to-End processing for Autonomous Driving

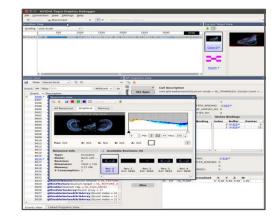


NVIDIA DEVELOPER TOOLCHAIN

 Vibrante Linux PDK Extract V4L packages for loc NV Toolchains Minimal Package OSS and NV packages OSS Ediose 64 	24.02.01	mixed no action install 24.02.01 install	Finished installing Pending install
NV Toolchains Minimal Package OSS and NV packages	24.02.01	install 24.02.01 Install	
 Minimal Package OSS and NV packages 	-	install	Pending install
OSS and NV packages			
	-		
OSS Eclipse 64		install 24.02.01	Pending Install
		install 24.02.01	Pending install
▼ CUDA		install	
CUDA on Host		install 7.0	Validating packages
CUDA on Target	a	Install 7.0	Pending install
Vibrante Linux Docs		install 1.1	Pending install
Tegra System Profiler	-	Install 2.4	Validating packages
Vibrante Foundation Packages		install	
Extract foundation packages	-	Inst 24.02.01	Validating packages
GNU Toolchains		install 24,02.01	Pending install
Vibrante Foundation Packages	12	install 24,02.01	Pending install
Vibrante Foundation OSS Pa		install 24.02,01	Pending install
Vibrante Foundation Docs	-	Install 24.02.01	Pending install
JetPack Documentation			Pending install
Flash OS	-		







DriveInstall

Easy installation Devkit flashing Sets up development environment

NVIDIA® Nsight[™] Eclipse Edition

CUDA build management CUDA kernel debugging and profiling CPU and GPU debugging Memory checker

Tegra System Profiler

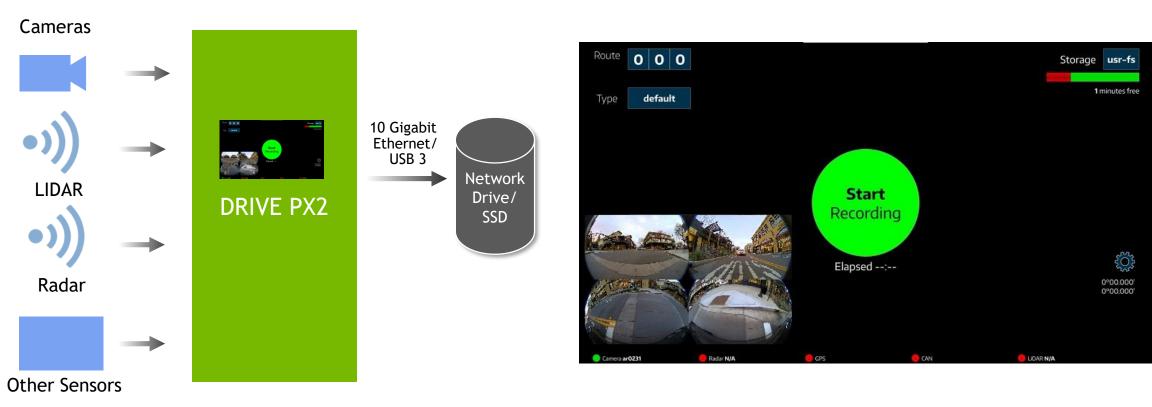
CPU sampling profiler Application Trace CUDA API & GPU trace OpenGL ES API & GPU trace Code decoration API/NVTX

Tegra Graphics Debugger

Performance monitoring Frame debugging Frame profiling

USECASE EXAMPLES

TOOLS - DATA ACQUISITION



Intuitive UI to enable simultaneous capture data from sensors

DEEP NEURAL NETWORKS IN DRIVEWORKS

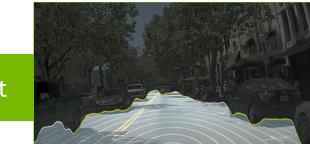




LaneNet

Lane detection

Multi-class detection: Cars, Pedestrian, Bicycles Upcoming: Lanes, Traffic signs



OpenRoadNet

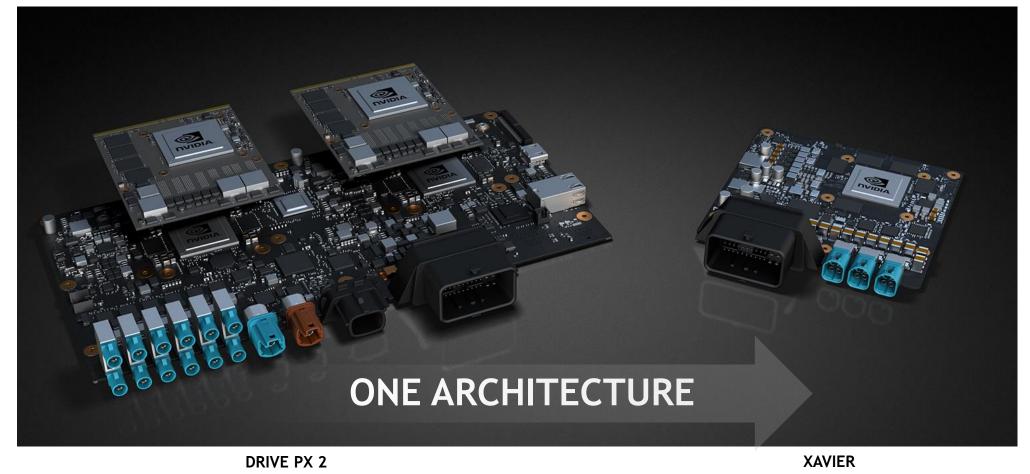
Free space detection



End to end in-lane driving

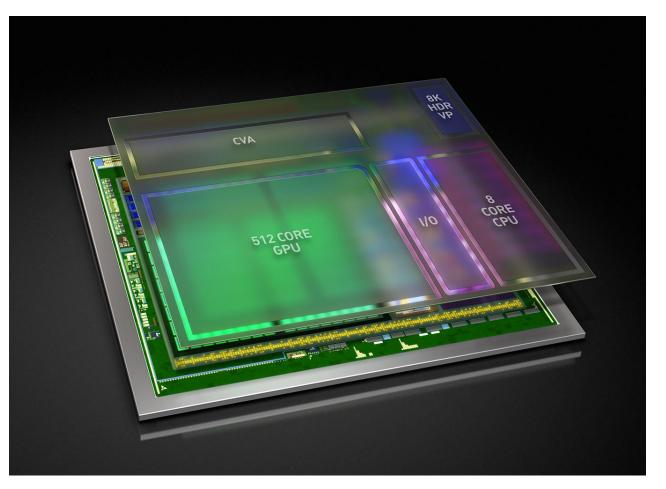
NEXT GENERATION AD SOLUTION

INTRODUCING XAVIER AI SUPERCOMPUTER SOC



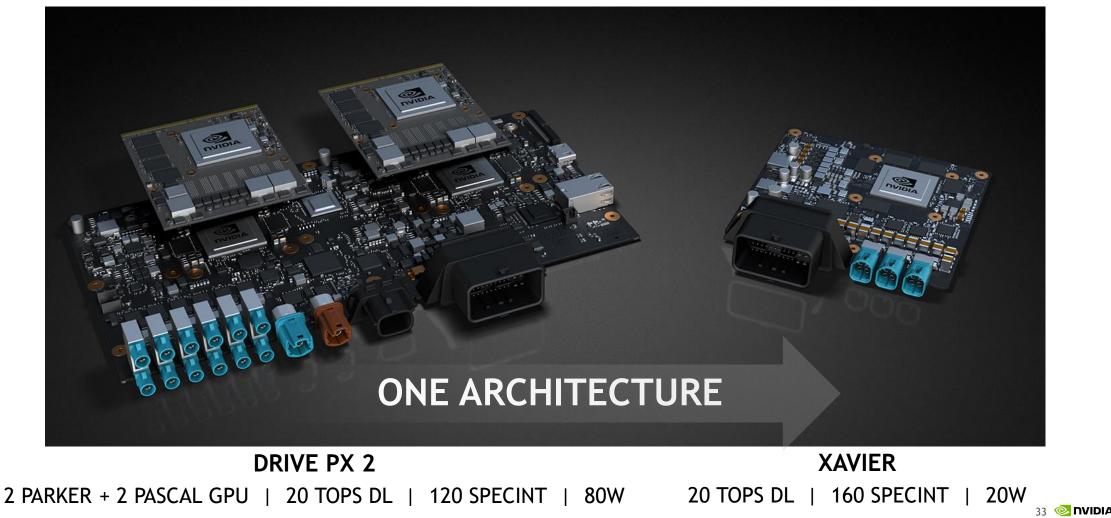
PARKER + 2 PASCAL GPU | 20 TOPS DL | 120 SPECINT | 80W 20 TOPS DL | 160 SPECINT | 20W

INTRODUCING XAVIER AI SUPERCOMPUTER SOC

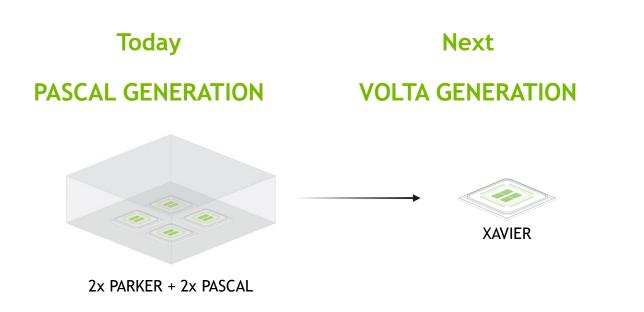


7 Billion Transistors 16nm FF
8 Core Custom ARM64 CPU
512 Core Volta GPU
New Computer Vision Accelerator
Dual 8K HDR Video Processors
Designed for ASIL C Functional Safety

INTRODUCING XAVIER AI SUPERCOMPUTER SOC



THE NEXT GENERATION DRIVE PX 2 IS THE TIME MACHINE TO XAVIER



SUMMARY

End-to-end Autonomous driving SDK

Targeted for both rapid prototyping and production

Integrated with OS, TensorRT, CUDA/CuDNN and VPI to offer comprehensive feature set

Optimized for Tegra SOC and NVIDIA GPU

NVIDIA support available